

EAST Search History

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
S1	317	program\$4 near4 (robotic adj2 arm)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/11/08 16:51
S2	3	program\$4 near4 (robotic adj2 arm) and toy	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/11/08 16:51
S3	1169	toy near3 robot	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/11/08 16:51
S4	245	(toy near3 robot) and program\$3 and input\$4	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/11/08 20:46
S6	7	"657032".ap.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/11/08 21:16
S7	759	(robot\$2 with input with movement)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/11/08 21:51
S8	373	(robot\$2 with input with movement) and memory	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/11/08 21:52
S9	157	(robot\$2 with input with movement) and memory and ((start\$3 or initial or final or end\$3) near3 (position))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/11/08 22:02

EAST Search History

S10	30	toy same robot same (reproduc\$3 or repeat\$3 or learn\$3) same (motion or movement)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/11/13 09:02
S11	1147	robot with learn\$3	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/11/13 09:02
S12	132	(robot with learn\$3) and toy	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/11/13 09:10
S13	7	(robot with learn\$3) and toy and (manual\$3 with input\$3)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/11/13 10:41
S14	305	901/3.ccls.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/11/13 10:56
S15	113	901/4.ccls.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/11/13 10:56
S16	317	program\$4 near4 (robotic adj2 arm)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/11/13 10:58
S17	3	program\$4 near4 (robotic adj2 arm) and toy	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/11/13 10:58

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S18	1171	toy near3 robot	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/11/13 10:58
S19	245	(toy near3 robot) and program\$3 and input\$4	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/11/13 10:58
S20	7	"657032".ap.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/11/13 10:58
S21	759	(robot\$2 with input with movement)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/11/13 10:58
S22	373	(robot\$2 with input with movement) and memory	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/11/13 10:58
S23	157	(robot\$2 with input with movement) and memory and ((start\$3 or initial or final or end\$3) near3 (position))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/11/13 10:58
S24	30	toy same robot same (reproduc\$3 or repeat\$3 or learn\$3) same (motion or movement)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/11/13 10:58
S25	1147	robot with learn\$3	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/11/13 10:58

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S26	132	(robot with learn\$3) and toy	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/11/13 10:58
S27	7	(robot with learn\$3) and toy and (manual\$3 with input\$3)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/11/13 10:58